

## Curvature of curves and surfaces

**Exercise 1** Curvature of plane curves. Let  $\gamma : I \rightarrow \mathbb{R}^2$  be a (smooth) curve parametrized with respect to arc length (i.e.  $T(s) = \gamma'(t)$  is a unit tangent vector). Let  $N : I \rightarrow \mathbb{R}^2$  be a unit normal vector field along  $\gamma$  such that  $(T(s), N(s))$  is a direct basis for all  $s \in I$ . Recall that the *signed curvature*  $\kappa$  is defined by

$$\gamma''(s) = \kappa(s)N(s).$$

1. Why is  $\gamma''(s)$  collinear to  $N(s)$  ?
2. Compute the curvature of a circle of radius  $R$ .
3. Compute  $N'(s)$ . Does the obtained formula remain correct if we change the parameterization of  $\gamma$  ?
4. Let  $\gamma$  be a curve of constant curvature. Prove that the image of  $\gamma$  is contained in a line or in a circle.
5. (Bonus) Let  $s \mapsto (x(s), y(s))$  be a (smooth) immersed parametric curve. Compute its curvature.

**Exercise 2** Gaussian curvatures of surfaces in  $\mathbb{R}^3$ . Let  $S$  be a (smooth) surface in  $\mathbb{R}^3$  and  $N : S \rightarrow \mathbb{S}^2$  be a (smooth) unit normal vector field for  $S$ .

1. Let  $p \in S$ . Explain why  $T_p N$  can be seen as an endomorphism of  $T_p S$ .
2. Let  $p \in S$ . Show that  $T_p N$  is a self-adjoint linear map.

As  $T_p N$  is self-adjoint, it is diagonalizable in an orthonormal basis. Let  $-k_1(p)$  and  $-k_2(p)$  be its eigenvalues and  $(e_1(p), e_2(p))$  an orthonormal basis of eigenvectors. Then  $k_1$  and  $k_2$  are called the *principal curvatures* and  $k_1 k_2$  is called the *Gaussian curvature* of  $S$ . Let  $\mathbb{II}$  be the quadratic form, called the *second fundamental form*, defined by

$$\mathbb{II}_p(u, v) = -\langle T_p N \cdot u, v \rangle$$

for all  $p \in S$ . Notice that if we change  $N$  to  $-N$ , we obtain opposite principal curvatures but the same Gaussian curvature.

3. Let  $p \in S$ . Write  $\mathbb{II}_p$  in the basis  $(e_1(p), e_2(p))$ .
4. Compute  $\mathbb{II}$ , the principal curvatures and the Gaussian curvature of
  - (a) the sphere of radius  $R$ ;
  - (b) the cylinder of axis  $(Oz)$  and radius  $R$ ;
  - (c) the hyperbolic paraboloid  $z = y^2 - x^2$  at  $(0, 0, 0)$ .
5. Let  $P$  be a affine plane such that  $p \in P$  and  $N(p) \in \vec{P}$ .
  - (a) Show that  $S \cap P$  is a smooth curve in a neighborhood of  $p$ .

Let  $\gamma_P$  be this curve. We choose an orientation for  $\gamma_P$  compatible with  $N$ .

(b) Compute the curvature of  $\gamma_P$  at  $p$  using  $\mathbb{II}_p$ .

(c) Prove that  $k_1(p)$  and  $k_2(p)$  are the maximum and minimum of the curvature of the curves  $\gamma_P$  for all  $P$  as above.

6. Let  $\gamma : I \rightarrow S$  be a (smooth) curve. We say  $\gamma$  is a *geodesic* for  $S$  if  $\gamma''(s)$  is collinear to  $N(\gamma(s))$  for all  $s \in I$ .

(a) Show that the parallels of the sphere  $\mathbb{S}^2$  (ie the great circles intersecting the poles) parametrized at constant speed 1 are geodesics of  $\mathbb{S}^2$ .

(b) Let  $C$  be the cylinder of axis  $(Oz)$  and radius 1. Let  $p = (1, 0, 0) \in C$ . Give a geodesic with initial point  $p$  and initial velocity  $v_1 = (0, 1, 0)$ . Same question with  $v_2 = (0, 0, 1)$  and (Bonus)  $v_3 = (0, u_0, v_0)$ .

7. Assume that  $S$  is connected and for all  $p \in S$ , we have  $k_1(p) = k_2(p) = \kappa$ . Show that  $S$  is contained in a plane or in a sphere.

8. (Bonus) Assume that  $S$  is connected and for all  $p \in S$ ,  $k_1(p) = k_2(p)$ . Show that the principal curvatures are constant.

9. (Bonus) Let  $p \in S$  and  $P$  be an affine plane such that  $p \in P$ . Let  $\gamma : I \rightarrow S \cap P$  be an immersed curve such that  $\gamma(0) = p$ . Compare the curvature of  $\gamma$  at 0 and  $\mathbb{II}(\gamma'(0))$ .

10. (Bonus - This question may involve more computations than the previous ones.)

(a) Compute the principal curvatures and the Gaussian curvature of a surface of revolution obtained by rotating  $u \mapsto (r(u), 0, z(u))$  around the  $z$ -axis (where  $r > 0$  and  $u \mapsto (r(u), z(u))$  is an immersion).

(b) Compute the principal curvatures of a torus of revolution given by the circle of radius  $r_2$  and center  $(r_1, 0)$  (where  $0 < r_2 < r_1$ ).

(c) Give a geometric interpretation of  $k_1$  and  $k_2$  (for the torus or in the general case of a surface of revolution)

(d) Compute the Gaussian curvature of the surface of revolution given by the tractrix  $u \mapsto (1/\cosh(u), u - \tanh(u))$ .

## References

For Exercise 2 - Questions 1 to 9. Manfredo P. do Carmo. *Differential Geometry of Curves and Surfaces*. Chapter 3.

For surfaces of revolution: *Pierre Pansu's webpage Cours de Géométrie Différentielle*  
[https://www.imo.universite-paris-saclay.fr/~pierre.pansu/web\\_dea/resume\\_dea\\_04.html](https://www.imo.universite-paris-saclay.fr/~pierre.pansu/web_dea/resume_dea_04.html)